

Online Nonnegative Tensor Factorization and CP Decomposition

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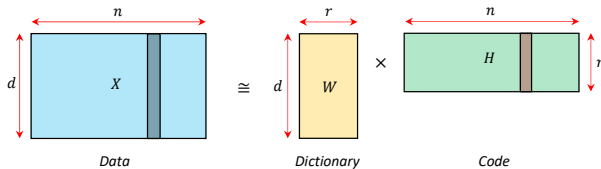
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Offline Matrix and Tensor Factorization

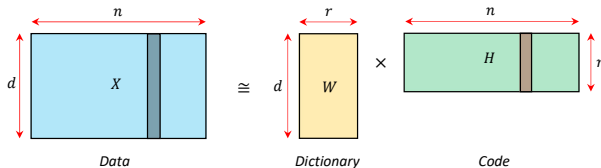
Online Matrix and Tensor Factorization

Algorithms for Online Matrix/Tensor Factorization

- ▶ **Matrix factorization** is a fundamental tool in dictionary learning problems.



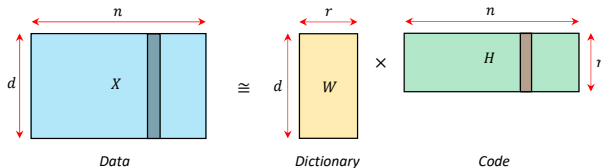
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- ▶ Formulated as a **non-convex** optimization problem:

$$\begin{cases} \text{minimize} & \|X - WH\|_F^2 + \lambda \|H\|_1 & (\text{Reconstruction error}) \\ \text{subject to} & W \in \mathcal{C}, H \in \mathcal{C}' & (\text{Constraints}) \end{cases}$$

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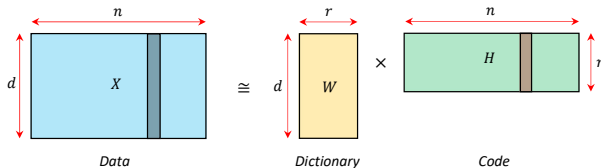


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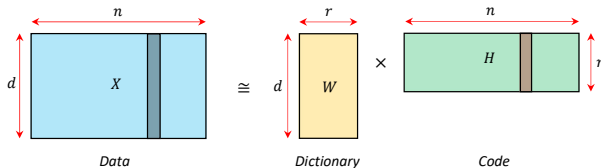
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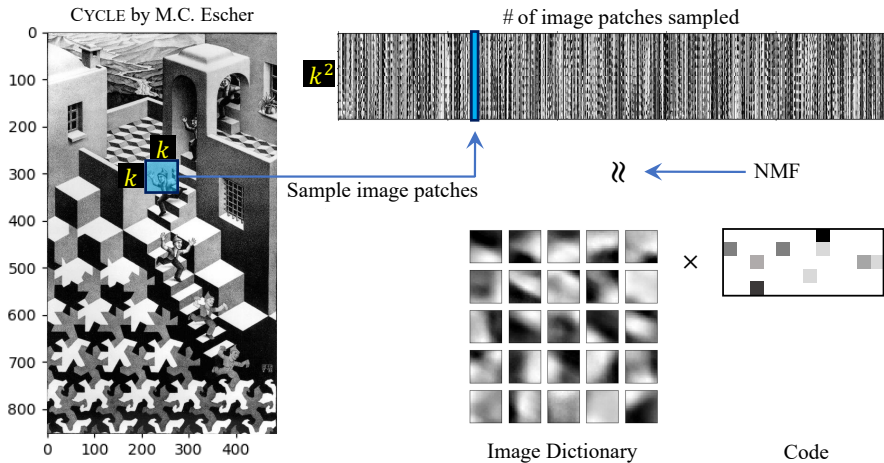
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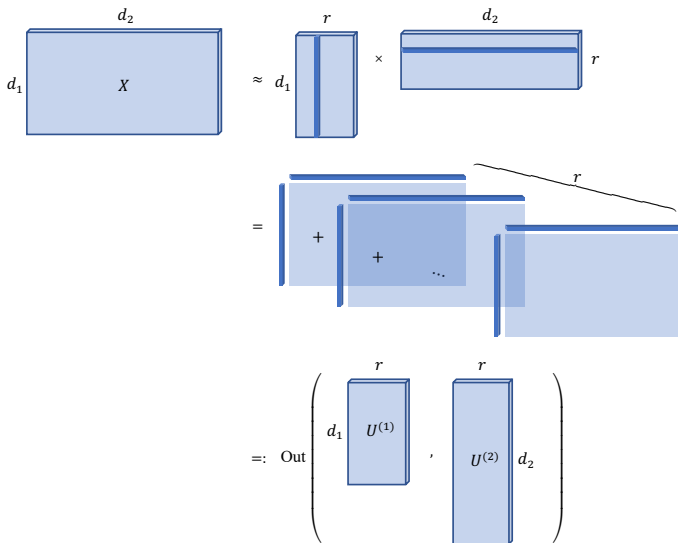
- ▶ Applications in text analysis, image reconstruction, medical imaging, bioinformatics, etc.

Example of NMF for Image dictionary learning

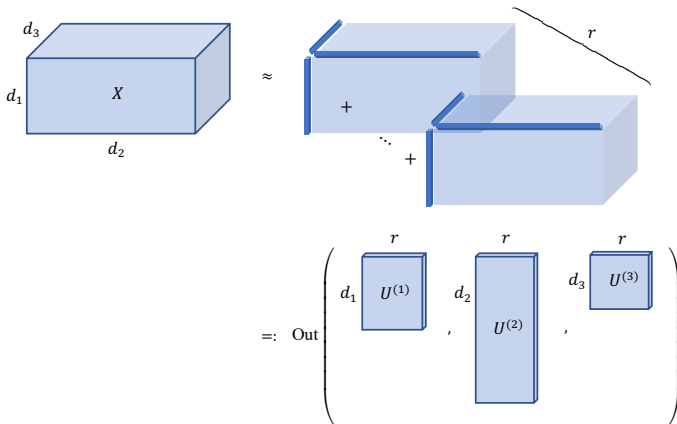


An alternative view of Matrix Factorization

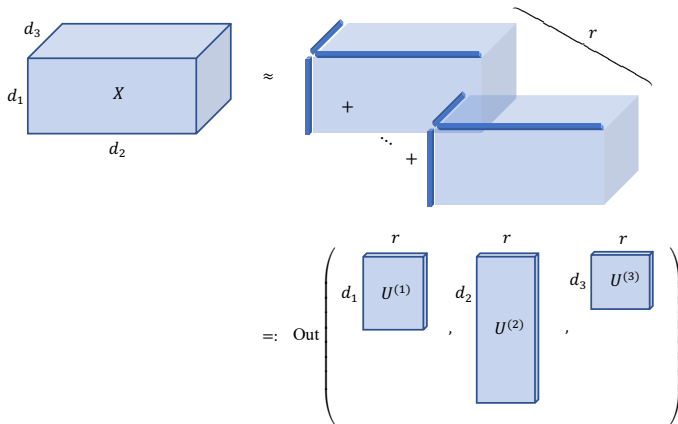
► $X \approx \text{Out}(U^{(1)}, U^{(2)})$



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► Nonnegative Tensor Factorization

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$$\begin{cases} U_t^{(1)} \leftarrow \underset{U \in \mathbb{R}_{\geq 0}^{d_1 \times r}}{\operatorname{argmin}} \|X - \operatorname{Out}(U, U_{t-1}^{(2)}, U_{t-1}^{(3)})\|_F^2 \\ U_t^{(2)} \leftarrow \underset{U \in \mathbb{R}_{\geq 0}^{d_2 \times r}}{\operatorname{argmin}} \|X - \operatorname{Out}(U_t^{(1)}, U, U_{t-1}^{(3)})\|_F^2 \\ U_t^{(3)} \leftarrow \underset{U \in \mathbb{R}_{\geq 0}^{d_3 \times r}}{\operatorname{argmin}} \|X - \operatorname{Out}(U_t^{(1)}, U_t^{(2)}, U)\|_F^2 \end{cases}$$

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- BCD for NTF is **not** guaranteed to converge to a stationary point of the loss function (Powell '73 [6])

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- Rate of convergence: $O((\log n)^2/n)$

Offline Matrix and Tensor Factorization

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Algorithms for Online Matrix/Tensor Factorization

► Online (Nonnegative) Matrix Factorization:

$$\operatorname{argmin}_{W \in \mathbb{R}_{\geq 0}^{d \times n}} \left(\ell(W) := \mathbb{E}_{X \sim \pi} \left[\inf_{H \in \mathbb{R}_{\geq 0}^{r \times d}} \|X - WH\|_F^2 \right] \right)$$

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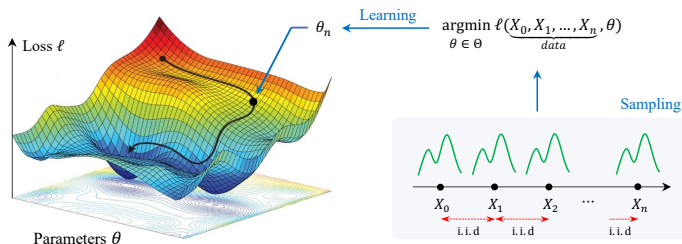
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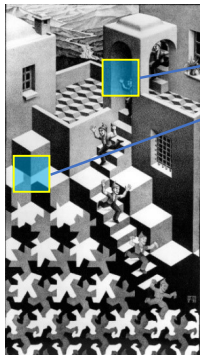
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- Why “online”?



Example of Online NMF + i.i.d. sampling: Image dictionary learning

CYCLE by M.C. Escher



**i.i.d.
sampling**

Minibatches of flattened
image patches

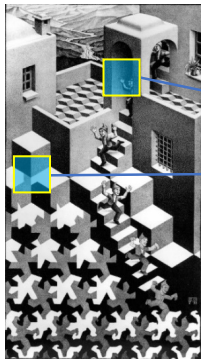


Online NMF

Dictionary₁

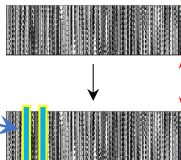
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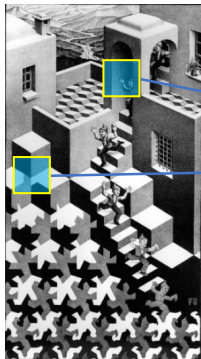
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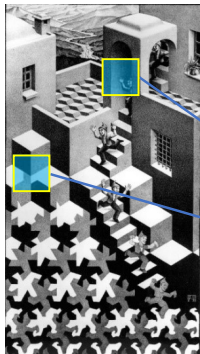
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...

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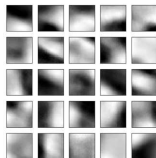
Online NMF

Dictionary₁

Dictionary₂

Dictionary₃

...



- ▶ Going from matrix factorization to **tensor factorization**
→ **Learn also from the time dimension**

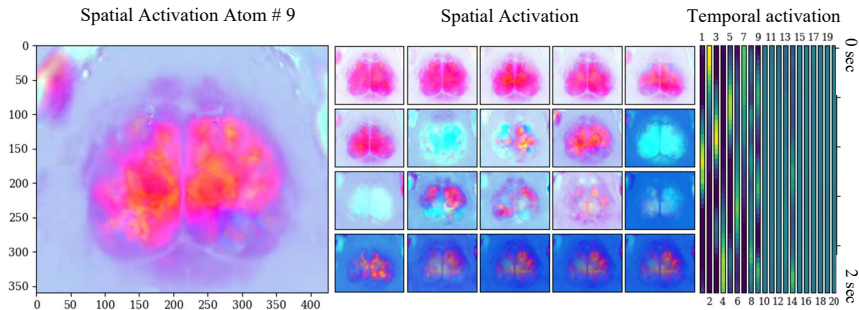


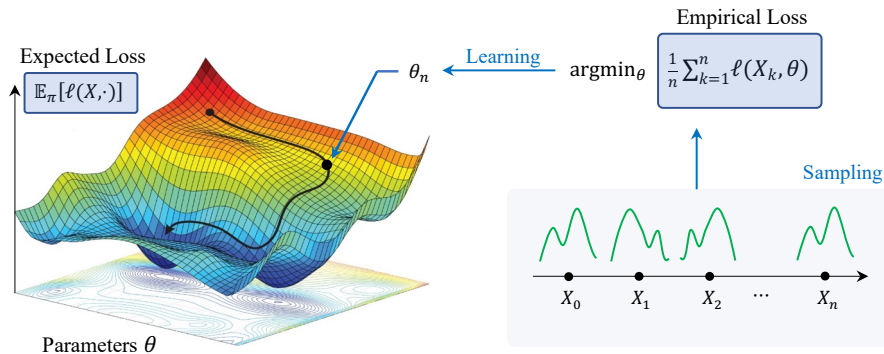
Figure: Temporal dictionary learned from mice brain activity video (Original data from Barson et al. *Nature methods* (2020))

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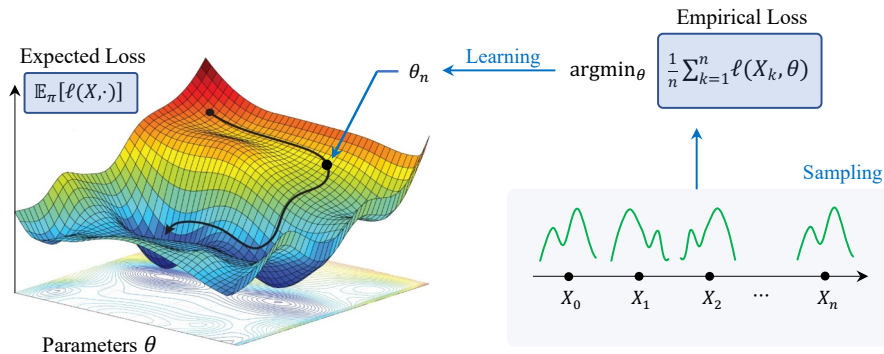
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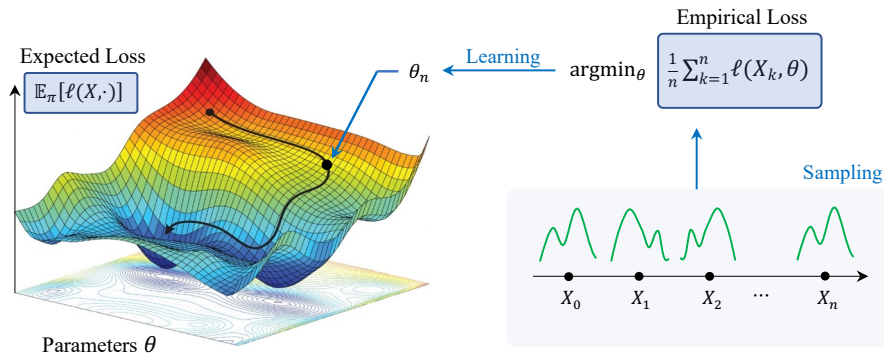
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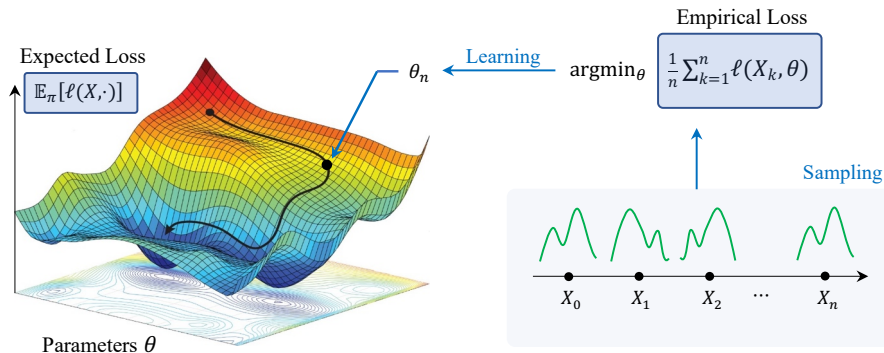
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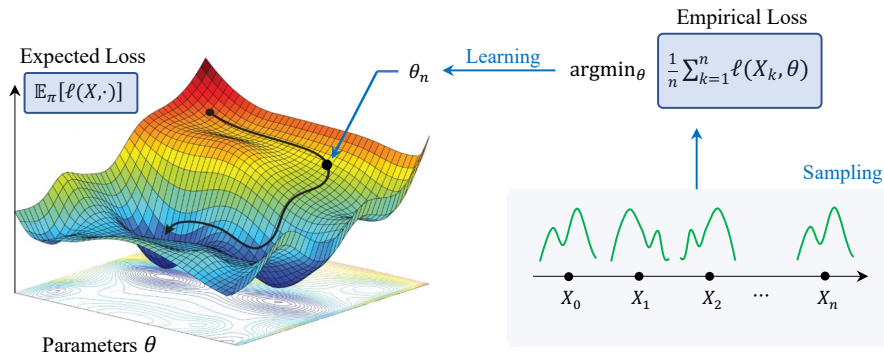
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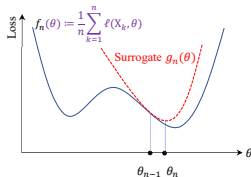
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 - Background: $\lim_{n \rightarrow \infty} \text{Empirical Loss} = \text{Expected loss}$
 - **Not practical** in many cases:
 - The *empirical loss is often hard to minimize* (e.g., Matrix/Tensor Factorization)

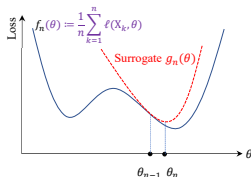


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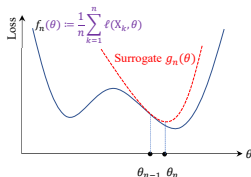


► Online NMF algorithm (Mairal, Bach, Saprio, Ponce [5]):

$$\begin{cases} H_t & \leftarrow \operatorname{argmin}_{H \in \mathbb{R}_{\geq 0}^{r \times n}} [\|X_t - W_{t-1} H\|_F^2] & (\text{Convex}) \\ \hat{f}_t(W) & \leftarrow (1 - w_t) \hat{f}_{t-1}(W) + w_t (\|X_t - W H_t\|_F^2) & (\text{Surrogate empirical loss}) \\ W_t & \leftarrow \operatorname{argmin}_{W \in \mathbb{R}_{\geq 0}^{d \times r}} \hat{f}_t(W) & (\text{Convex}) \end{cases}$$

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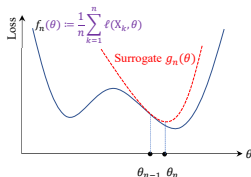
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- Algorithm converges to a stationary point almost surely

► Stochastic Majorization-Minimization (SMM) – Mairal [4]

- Iteratively minimize majorizing surrogates g_n of the empirical loss f_n :



► Online NMF algorithm (Mairal, Bach, Saprio, Ponce [5]):

$$\begin{cases} H_t & \leftarrow \operatorname{argmin}_{\substack{H \in \mathbb{R}^{r \times n} \\ \geq 0}} [\|X_t - W_{t-1}H\|_F^2] & (\text{Convex}) \\ \hat{f}_t(W) & \leftarrow (1 - w_t)\hat{f}_{t-1}(W) + w_t (\|X_t - WH_t\|_F^2) & (\text{Surrogate empirical loss}) \\ W_t & \leftarrow \operatorname{argmin}_{\substack{W \in \mathbb{R}^{d \times r} \\ \geq 0}} \hat{f}_t(W) & (\text{Convex}) \end{cases}$$

- Algorithm converges to a stationary point almost surely
- Convergence also holds when data sequence has Markovian dependence (Lyu, Needell, Balzano [3])

- Online NTF algorithm (?):

$$\left\{ \begin{array}{ll} U_t^{(3)} & \leftarrow \operatorname{argmin}_{U^{(3)} \in \mathbb{R}_{\geq 0}^{d_3 \times r}} \left[\left\| X_t - \text{Out}(U_{t-1}^{(1)}, U_{t-1}^{(2)}, U^{(3)}) \right\|_F^2 \right] \quad (\text{Convex}) \\ \hat{f}_t(U^{(1)}, U^{(2)}) & \leftarrow (1 - w_t) \hat{f}_{t-1}(U^{(1)}, U^{(2)}) \\ & \quad + w_t \left(\left\| X_t - \text{Out}(U^{(1)}, U^{(2)}, U_t^{(3)}) \right\|_F^2 \right) \quad (\text{Surrogate empirical loss}) \\ (U_t^{(1)}, U_t^{(2)}) & \leftarrow \operatorname{argmin}_{U^{(1)} \in \mathbb{R}_{\geq 0}^{d_1 \times r}, U^{(2)} \in \mathbb{R}_{\geq 0}^{d_2 \times r}} \hat{f}_t(U^{(1)}, U^{(2)}) \quad (\text{Non-convex}) \end{array} \right.$$

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- Surrogate empirical loss $\hat{f}_t$ is non-convex, so cannot directly find minimizing $(U_t^{(1)}, U_t^{(2)})$.

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- $(U_t^{(1)}, U_t^{(2)})$ does **not** minimize $\hat{f}_t$
- No convergence guarantee to stationary points

- Online NTF algorithm (!) (Strohmeier, Lyu, Needell [7]):

$$\left\{ \begin{array}{ll} U_t^{(3)} & \leftarrow \operatorname{argmin}_{U^{(3)} \in \mathbb{R}_{\geq 0}^{d_3 \times r}} \left[\left\| X_t - \text{Out}(U_{t-1}^{(1)}, U_{t-1}^{(2)}, U^{(3)}) \right\|_F^2 \right] \quad (\text{Convex}) \\ \hat{f}_t(U^{(1)}, U^{(2)}) & \leftarrow (1 - w_t) \hat{f}_{t-1}(U^{(1)}, U^{(2)}) \\ & \quad + w_t \left(\left\| X_t - \text{Out}(U^{(1)}, U^{(2)}, U_t^{(3)}) \right\|_F^2 \right) \quad (\text{Surrogate empirical loss}) \\ U_t^{(1)} & \leftarrow \operatorname{argmin}_{U^{(1)} \in \mathbb{R}_{\geq 0}^{d_1 \times r}, \|U^{(1)} - U_{t-1}^{(1)}\|_F \leq w_t} \hat{f}_t(U^{(1)}, U_{t-1}^{(2)}) \quad (\text{Convex}) \\ U_t^{(2)} & \leftarrow \operatorname{argmin}_{U^{(2)} \in \mathbb{R}_{\geq 0}^{d_2 \times r}, \|U^{(2)} - U_{t-1}^{(2)}\|_F \leq w_t} \hat{f}_t(U_t^{(1)}, U^{(2)}) \quad (\text{Convex}) \end{array} \right.$$

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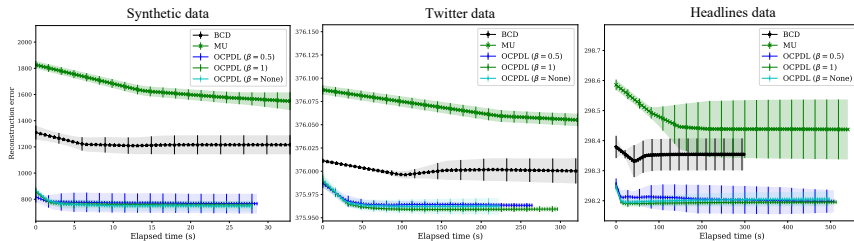
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- But we can get a.s. convergence to stationary points [7]

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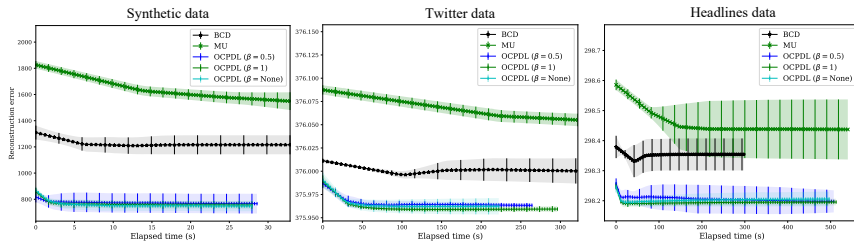
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- $(U_t^{(1)}, U_t^{(2)})$ still does **not** minimize $\hat{f}_t$
- But we can get a.s. convergence to stationary points [7]
- Rate of convergence: $O((\log n)/n^{1/4})$ (Upcoming paper)

- Comparison of Online NTF against BCD (ALS) and Multiplicative Update (MU) on offline NTF:



- Comparison of Online NTF against BCD (ALS) and Multiplicative Update (MU) on offline NTF:



- Online NTF outperforms both ALS and MU on all three datasets

Thanks!

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